Md Ashfaqur Rahaman

	Research Interests
	Kernel bypass, disaggregated memory, hardware offloading and systems for machine learning
	Education
Aug. 2021	Ph.D. in Computer Science , <i>University of Utah</i> , Salt Lake City, Utah, USA Advisor: Ryan Stutsman
2012-2019	B.Sc. in Naval Architecture and Marine Engineering , <i>Bangladesh University of Engineering and Technology (BUET)</i> , Dhaka, Bangladesh
	Experience
	Research
Summer 2024	Research Intern , <i>Hewlett Packard Labs</i> , Milpitas, California Optimizing the communication infrastructure to support low-latency high-throughput LLM inference
2021-Present	 Graduate Research Assistant, Utah Scalable Computer Systems Lab, University of Utah, Utah A new efficient, secure, and scalable framework for remote memory access and function offloading exploiting the programmability and offloading capability of smartNICs A new software architecture for building services that centers around coherent accelerators and rack-scale shared memory
2019-2021	Research Assistant , <i>Prof. Baris Kasikci's Lab</i> , University of Michigan, Ann Arbor <i>Mentor: Tanvir Ahmed Khan</i> Load-time code layout optimization of large application binaries in warehouse scale computers
2018-2019	Research Assistant , <i>Climate Modeling and Simulation Lab</i> , IWFM, BUET <i>Advisor: A.K.M. Saiful Islam</i> I worked as a system developer in real-time Flash Flood Early Warning System (FFEWS) project
	Professional
2018-2019	Software Engineer , <i>NextGen DigiTech</i> , Dhaka I worked on NextGen Tower, a desktop application for designing wind turbines. I contributed in the core software architecture and developed the GUI.
2017-2018	Firmware Engineer , <i>2RA Technology Limited</i> , Dhaka I worked on various embedded systems projects based on Raspberry Pi and AVR Microcontrollers.
	Selected Research Projects
2021-Present	NIC Accelerated Active Messaging
	RDMA is gaining popularity in datacenters for high-throughput and low-latency network communication for building dis-aggregated systems. However, there are many issues that are holding RDMA back from being widely deployed. Current RDMA verbs are limited for diverse workloads, they are difficult to program, and multiple round trips are required to do complicated memory operations e.g. walking a hash table. We are working on creating a new network abstraction to make remote memory access more efficient, secure, and scalable exploiting the programmability and offloading feature of smartNICs. In our system, NIC offloads can be written in a high level language ensuring easy programmability, then this will be converted into verifiable bytecode tailored to a specific workload and run on the NIC or host based on the dynamic load. Program transformation, dynamic

decisions, all these will be transparent to the developer.

2023-Present Software Architectures for Large-Scale Coherent Shared Memory

Emerging standards for cache coherent accelerators (e.g. CXL) will soon transform how memory-intensive large-scale systems are developed. Cache coherent accelerators are programmable (via FPGAs), and they can interpose on CPU memory accesses at cache line granularitiy. Low-overhead, granular access tracking with these coherent accelerators enable efficient memory disaggregation. But disaggregation alone will not fundamentally change application architecture. In this work we are designing a new software architecture for building large scale services that centers around coherent accelerators and rack-scale shared memory.

Selected Courses

- Fall 2024 Advanced Compilers, University of Utah
- Spring 2024 Advanced Computer Architecture, University of Utah
- Fall 2023 Advanced Networking, University of Utah
- Spring 2022 Software Security, University of Utah
 - Fall 2021 Advanced Operating Systems, University Of Utah

Teaching Assistantship

- Fall 2022 Distributed Systems, University Of Utah
- Spring 2022 Operating Systems, University Of Utah

Services

- 2022 Artifact Evaluation Committee Member, OSDI'22
- 2021 Artifact Evaluation Committee Member, SOSP'21

Bachelor Thesis

Title Power Efficient Remotely Operated Underwater Vehicle Using Buoyancy Chambers Supervisor Dr. Md. Mashud Karim

Skills

Languages C, C++, Rust, CUDA, Python, Go, Assembly(ARM, X86) Tools CXL, eBPF, RDMA, DPDK, Pytorch, NVIDIA DOCA, LLVM, Linux perf, BOLT Platforms NVIDIA BlueField 2, AVR Microcontrollers, Raspberry Pi, Arduino Text Editing Vim, LATEX